JAMIA MILLIA ISLAMIA

(A Central University by an Act of Parliament)

Tel. 26982651 26981717 Ext.: 2340, 2342 e-mail: electrical@jmi.ac.in

Website: https://www.jmi.ac.in

DEPARTMENT OF ELECTRICAL ENGINEERING

Faculty of Engineering and Technology Maulana Mohammed Ali Jauhar Marg, New Delhi-110025

EED/Q-01/2024/25

January 28, 2025

LIMITED TENDER NOTICE

The Department of Electrical Engineering, Jamia Millia Islamia, New Delhi, invite quotations for the following items as per University Purchase procedure. It is requested to kindly provide us sealed quotations/e-mail <electrical@jmi.ac.in> of these items along with their specifications, if any. The quotation may be submitted within a day's up to 07/02/2025 in the office of the undersigned.

S. No.	Particular and Technical Specification	Unit Rate	Tax	Total Amount
1	Humanoid Robot	01		
	Technical Specification			
	Dimensions W x L x H 150 *130 *330 (mm)			
	Connectivity Wi-Fi connectivity (ad- hoc/infrastructure/WEP/WPA/WPA2)			
	On-board Computer 220MHz 32-bit total processing with two 32-bit ARM Cortex processors			
	Amplified speaker for streaming speech and music audio			
	IO Ports 1 x real-time EZ-B v4 Camera port 8 x 5 volt tolerant analog (ADC) ports 24 x 5 volt tolerant digital ports (servos, PWM, and more) Supports up to 73 servos (combining PWM and Dynamixel) 3 x I ² C ports 3 x high speed UART ports Battery and temperature monitor			
	Servo Motor Operating speed: 0.22±0.01 sec/60° (7.4v) Running current: 1400±30mA (7.4v) Stall torque: 19±0.20kg·cm (7.4v) Stall current: 3000±50mA (7.4v)			
	Supported Software and APIs OEM Software which supports RoboScratch and Blockly. Text-based coding languages like JavaScript, and EZ-Script (a C# derivative).			

		0.1		
2	ROLI Rover	01		
	Technical Specification	1		
	Rover-style robot that inspires teaching and empowers			
	learning.		1	
	Support for complex technologies such as:			
			1	
	Object tracking, Speech recognition,			
	Artificial intelligence (AI) and Machine learning.			
	HDD Servos			
3	SIX Hexapod			
	Hexapod/Quadpod Carbon fibre frame			
	~40-60 min flying time			
	3.3 kg MTOW			
	upto 16 m/s Max Speed			
	440 m VLOS Range			
	upto 6 m/s Wind Resistance	*		
	upto 400 ft Operational Altitude High resolution Camera Payload			
4	Adventure Bot			
	Autonous Dov			
	AI application practice equipment based on indoor service			
	robot platform			
	NVIDIA high-performance on-device AI platform is			
	adopted for Brain board			
	Touch display and high-resolution wide-angle camera for GUI-based user interface and deep learning are provided			
	Gigabit Ethernet, dual-band Wi-Fi, and Bluetooth are			
	provided			
	Voice recognition and audio playback through digital			
	microphone and speaker are possible			
	Various IoT sensor modules through 4 dedicated			
	expansion interfaces are supported For precise control of the driving part, controller equipped			
	with a high-performance MCU controls omni wheel	:		
	motor, encoder and sensor			
	Connected via highly reliable CAN FD communication for			
	collaboration between brain board and controller			
	Built-in power path management circuit to make it			
	possible to continue practicing even while the battery is			1
	charging Service robot development is supported through ROS2,			
	robot standard middleware			
	High-level Pop libraries enabling to focus on application			
	implementation is provided			
	CUDA-based PyTorch and Tensorflow artificial			
	intelligence framework are supported Web browser-based Google block coding platform			
	(Blockly) is supported			
	Pre-set integrated development environment based on		1	
	Visual Studio Code for professional application			
1	development is supported			
1	Deep learning-based service robot learning contents are			
	provided On-device AI self-driving car training equipment	1		
	The driving part adopts a 3-axis omni wheel to maximize the	1		
	robot's movement			

5	Robot Developer's Kit	
	AI-based developer kit Computer Vision Navigation Deep Learning Integration Intelligent Speech Processing Python, ROS, Gazebo support Arduino/Raspberry PI controller HD Camera LIDAR	
6	Data Analyzing Kit	

(20/01/2015)

(Prof. Shahida Khatoon)

Head

Notes:

- Quotation should be sealed in a separate envelope/item wise duly super scribed "Item name" Quotation reference No.: ------
- > Applicable Taxes, Warranty, Delivery period and other Terms & Conditions should be mentioned clearly
- > The quotation should be a reputed and an authorized firm/supplier having after sales service agreement with the OEM (Proof for the same to be enclosed along with address, phone nos. & E-mail etc. of the Service Centre).
- ➤ The quotation document complete in all respects should reach The Head, Department of Electrical Engineering, Faculty of Engineering and Technology, Jamia Millia Islamia, New delhi-110025
 - O (Attn. Head, Department of Electrical Engineering should be written over the sealed envelope)